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<input type="checkbox"/>	L35	displacement and L34	260
<input type="checkbox"/>	L34	linkage and L33	603
<input type="checkbox"/>	L33	support and sensor and L32	4637
<input type="checkbox"/>	L32	robot and sensor and substrate	6630
<input type="checkbox"/>	L31	robot and sensor and substrate sपोर्ट	0
<input type="checkbox"/>	L30	correct\$3 and position and sensor and substrate sपोर्ट	0
<input type="checkbox"/>	L29	(correct\$3 and position and sensor) and substrate sपोर्ट	0
<input type="checkbox"/>	L28	(correct\$3 and position and sensor) same substrate sपोर्ट	0
<input type="checkbox"/>	L27	correct\$3 and positoin and substrate sपोर्ट and sensor	0
<input type="checkbox"/>	L26	(correct\$3 and positoin) same substrate sपोर्ट and sensor	0
<input type="checkbox"/>	L25	(correct\$3 and positoin and sensor) same substrate sपोर्ट	0
<input type="checkbox"/>	L24	correct\$3 and L23	19
<input type="checkbox"/>	L23	sensor and L22	33
<input type="checkbox"/>	L22	robot and L21	52
<input type="checkbox"/>	L21	bacchi.in.	171
<input type="checkbox"/>	L20	bacchi.in. and substrate and sensor	0
<input type="checkbox"/>	L19	bacchi.in. and substrate and sensor and motor	0
<input type="checkbox"/>	L18	bacchi.in. and substrate and sensor and motor and displacement	0
<input type="checkbox"/>	L17	bacchi.in. and substrate and sensor and motor and displacement and correct\$3	0
<input type="checkbox"/>	L16	bacchi.in. and substrate and sensor and motor and displacement and correct\$3 and position	0
<input type="checkbox"/>	L15	bacchi.in. and substrate and sensor and motor and displacement and correct\$3 and position and central axis	0
<input type="checkbox"/>	L14	bacchi.in. and substrate and sensor and motor and displacement and correct\$3 adn position and axis	0
<input type="checkbox"/>	L13	bacchi.in. and substrate and sensor and motor and displacement and correct\$3 adn position and central axis	0
<input type="checkbox"/>	L12	L8 and L9	73
<input type="checkbox"/>	L11	L8 and L9 and L10	26
<input type="checkbox"/>	L10	central axis and L9	49563
<input type="checkbox"/>	L9	predetermin\$3 or "pre-defin\$3" and L8	2638309
<input type="checkbox"/>	L8	support and L7	77
<input type="checkbox"/>	L7	displacement and L6	80
<input type="checkbox"/>	L6	L4 and L5	111

<input type="checkbox"/>	L5	correct\$3 same position	341543
<input type="checkbox"/>	L4	robot and motor and control\$3 and substrate and sensor and position and optical and capacitor and magnetic	222
<input type="checkbox"/>	L3	bacchi.in.	171
<input type="checkbox"/>	L2	yim.in. and robot and substrate	10
<input type="checkbox"/>	L1	10/697731	1

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"substrate support" robot displacement correct



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[Detection system for substrate clamp - Patent 6313596](#)

A **substrate support** member for a **robot** operable in a semiconductor processing ... 16, the **displacement** distances of the second and third substrates 114, ...

www.freepatentsonline.com/6313596.html - 68k - [Cached](#) - [Similar pages](#)

[Detection system for substrate clamp - Patent 6166509](#)

(c) a **substrate support** member movable through the enclosure, comprising: ... incremental **displacement** of the support member 66 caused by the **robot** 62. ...

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[SMD placement: Turning concepts into output :: EM ASIA is the ...](#)

After picking, each **robot** will move the component to the **correct** ... Feeder index movement limitations (depending on **displacement** between 2 feeders needed ...

www.emasiamag.com/article.asp?articleid=164 - [Similar pages](#)

[EP1465012 Asml european software patent - Supporting structure for ...](#)

The supporting structure may be a **robot** (8). The **robot** (8) has a **robot** arm (10) with a ... The **robot** arm comprises one or more compliant parts (14; 26; 28). ...

gauss.ffii.org/PatentView/EP1465012 - 71k - [Cached](#) - [Similar pages](#)

[\[PDF\] Derwent](#)

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surface of **substrate support** chuck, used to support a substrate within a ... **displacement** of wafer (W) with respect to both surfaces is measured by ... scientific.thomson.com/ts/media/dw/productpdfs/itppdfs/itsetes.pdf -

[Similar pages](#)

[SPIE Proceedings Vol. 2871](#)

The basic components of 2dF are the corrector lens optics, the **robot** which ... This effect became apparent when this system was applied to **correct** the ...

www.spie.org/web/abstracts/2800/2871.html - 90k - [Cached](#) - [Similar pages](#)

[United States Patent: 6571657](#)

The **substrate support** pins 906 preferably comprise distally tapered members ... **Robot** blades 3508, 3510, and 3512 are then adjusted by **displacement** of the ...

patft.uspto.gov/netacgi/nph-Parser?Sect2=PTO1&

Sect2=HITOFF&p=1&u=%2Fnetacgi%2Fsearch-bool.ht... - 195k -

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United States Patent: 5377002

For unambiguous identification of the **correct** positioning of the lens after it is ... A handling **robot** 105 is placed between the wafer cassettes 109, 110.

...

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Sect2=HITOFF&p=1&u=%2Fnetacgi/nph-Parser?Sect2=PTO1&
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Lithographic support structure patent invention

[0079] By providing the **robot** arm 10 with at least one of the compliant parts 14, 26, a tilt and/or a **displacement** in z between the substrate W and another ...

www.freshpatents.com/ Lithographic-support-structure-
dt20041209ptan20040246459.php - 102k - Cached - Similar pages

DoD SBIR FY01.2 - SOLICITATION SELECTIONS w/ ABSTRACTS

However, without the **correct** fluid handling systems and electrode placement physical ... PackBot is an extremely robust tracked **robot** with all-weather and ...

www.dodsbir.net/selections/abs012/dodabs012.htm - 977k -
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